

# Advanced Estimation of Remaining Useful Lifetime for Power Modules

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# Importance of Reliability

- **Unplanned downtime** costs world's 500 biggest companies **11%** of their revenues [1].

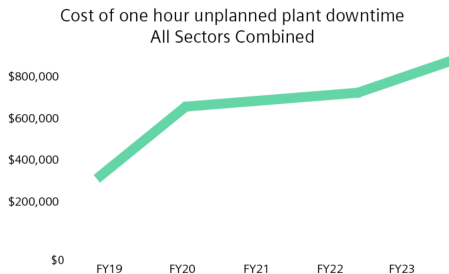


Figure 1: Source: Siemens | The True Cost of Downtime 2024 [1]

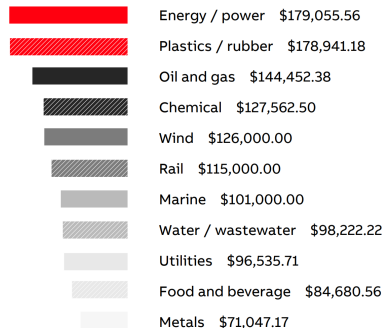


Figure 2: Source: Value of Reliability | ABB Survey Report 2023. [2]

# Importance of Reliability

- **Unplanned downtime** costs the 500 biggest companies **11%** of their revenues [1].
- **IOT** has allowed companies to collect data on the **condition** of their machines.
- **Predictive Maintenance with Remaining Useful Lifetime (RUL)** prediction allows to avoid failures and over-maintenance.

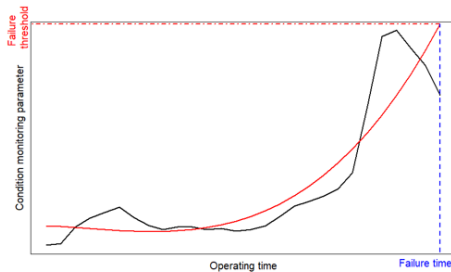


Figure 3: Typical RUL prediction approach.

- **Power modules** (PM) are widely used in inverters and power conversion equipment.
- Surveys [3] concluded that PMs (IGBT) were chosen by 31% of respondents as **fragile components**.
- Power module degradation is inherent and it is ongoing with operations.



Figure 4: Power module [4].

## Typical Degradation Mechanisms

- Die attachment delamination,
- Solder joint cracking,
- Bond wire fatigue.

## Die attachment delamination - Physical Model:

- VDS increases due to impaired thermal resistance,
- Cubic polynomial matches known physics of fatigue crack propagation and captures degradation.

## Two-Phase Behavior

- Early phase: High variance - measurement effects,
- Late phase: Low variance - dominant failure mechanism.

# Problem statement

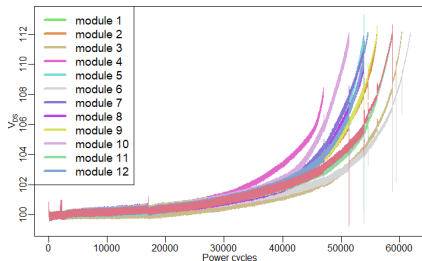


Figure 5: Power module degradation data.

- PMs show **linear drift** at early stages, followed by an **exponential degradation** pattern.
- Once **voltage drain source** ( $V_{DS}$ ) is above a certain threshold, the module is considered to have reached its **end of life**.
- A scenario of **on-line RUL** prediction with **limited calculation resources** is considered.

# Further patterns in stress test data

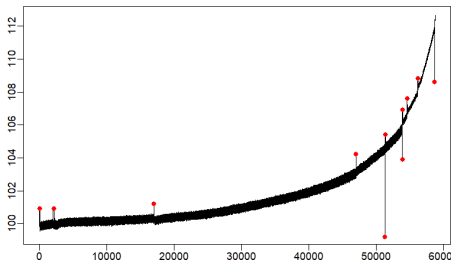


Figure 6: Measurement errors.

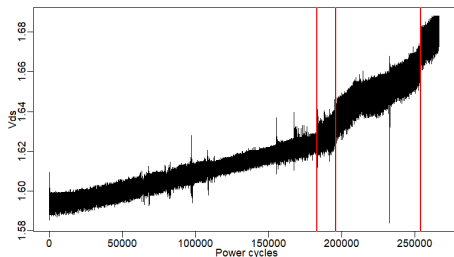


Figure 7: "Up-jumps" after additional deviation mechanisms.

# Two-regime Modelling

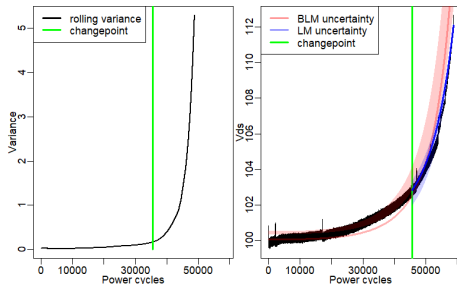


Figure 8: The proposed framework.

To capture degradation, we propose a heteroscedastic model that partitions the degradation process into two phases:

$$\sigma_t^2 = \begin{cases} \sigma_{high}^2 & \text{if } t < \tau_{cp}, \\ \sigma_{low}^2 & \text{if } t \geq \tau_{cp}, \end{cases}$$

where  $\tau_{cp}$  represents the changepoint time.



When only few degradation data are available, we use a Bayesian regression. For this, we apply normally distributed priors to the regression coefficients:

$$\beta_0 \sim \mathcal{N}(\mu_{\beta_0}, \sigma_{\beta_0}^2(t)),$$

$$\beta_1 \sim \mathcal{N}(\mu_{\beta_1}, \sigma_{\beta_1}^2(t)).$$

where  $\mu_{\beta_j}$  and  $\sigma_{\beta_j}^2$  are computed empirically.

By varying  $\sigma_{\beta_j}^2$ , the impact of the priors can be controlled:

- Initial:  $\sigma_{\beta_i}^2(t) = 10^{-10}$  (highly informative).
- Evolution: Gradually increase to  $\sigma_{\beta_i}^2$ .
- Transition triggered by changepoint at  $\tau_{cp}$ .

# Polynomial regression

As more data is collected, we transition to a polynomial regression after the changepoint:

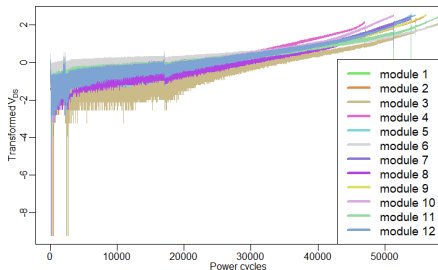


Figure 9: Data transformation.

First, a log-transformation is applied to  $V_{DS}$ :

$$y = \log(V_{DS} - \min(V_{DS}) + \phi),$$

with  $\phi = \varepsilon_{\log}$  is a correction term to avoid singularities.

Then, the cubic polynomial model of the form is used:

$$y = \beta_0 + \beta_1 t^3 + \varepsilon.$$

## Polynomial regression contd.

For each new data point, we determine  $\hat{\beta}_0$  and  $\hat{\beta}_1$  based on the least squares criterion:

$$\min_{\beta_0, \beta_1} \sum_{i=1}^k (y_i - (\beta_0 + \beta_1 x_i)) ^2,$$

where  $k \in \{1, \dots, n\}$ ,  $1 \leq k$ , and  $1, n \in \mathbb{N}$ .

# The Rolling Window Approach

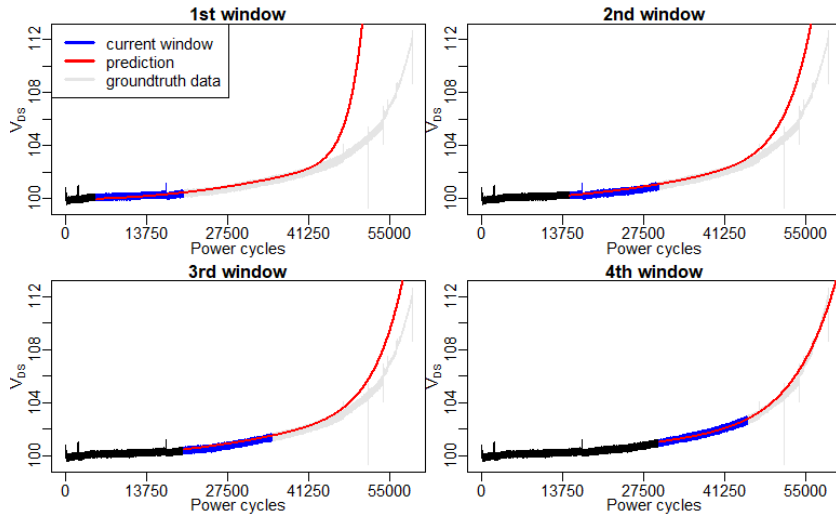


Figure 10: Window algorithm.

- **Heteroscedastic Variance Modeling**

- Adaptive variance:  $\sigma_t^2 = f(t, \tau_{cp})$ .
- Rolling window estimation:  $\hat{\sigma}_t^2 = \frac{1}{w} \sum_{i=t-w+1}^t (y_i - \hat{y}_i)^2$ .

- **Changepoint Detection**

- $\tau_{cp} = \frac{\hat{\sigma}_t^2}{\hat{\sigma}_{tw_1}^2}$ .
- Triggers variance regime transition.

- **Asymmetric Uncertainty Bounds**

- Lower bound:  $\alpha_1 = 0.03$ , Upper:  $\alpha_2 = 0.07$ .
- Late failures reduced:  $8.3\% \rightarrow 0.8\%$ .

- **Optimization is on the prediction error.**
- Adaptive Prediction Intervals combines parameter uncertainty, bias, and observation noise.

$$s_t^{*2} = \mathbf{x}_t^{*T} \text{Cov}[\beta | y_{1:t}] \mathbf{x}_t^* + \hat{\sigma}_t^{*2}.$$

- Weighted regression to improve accuracy of estimation of  $\beta$ .

# Prediction Accuracy Comparison

Model	20%	50%	90%
<b>Proposed model</b>	-6409	-5306	<b>-1775</b>
log-Gamma GLM	-5693	12906	13996
inv-Gamma GLM	-6685	11658	14474
FB Prophet	NA	109882	22523
ARIMA	NA	173159	19378
GPR	NA	29390	6906

## Key Achievements:

- 90% reduction in late failures.
- Best accuracy with minimal resources.
- Suitable for Edge-deployment.

- Further accuracy improvement.
- Comparison of calculation resources of AI methods with the proposed method.
- Assess impact on qualification strategy.
  - Use of generic data.
  - End-of-life tests on generic family parts (reference parts)
  - Qualification tests to verify degradation paths (parts to be qualified).



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Thank You!

